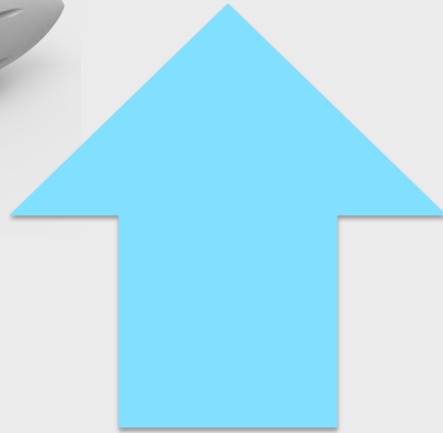
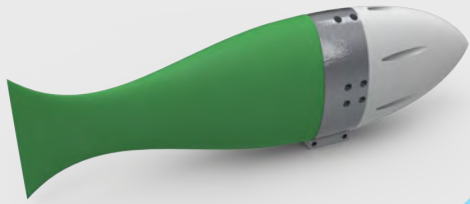


# Fish and fish robots: how can they help to understand each other?



# Biomimetics - a two way street



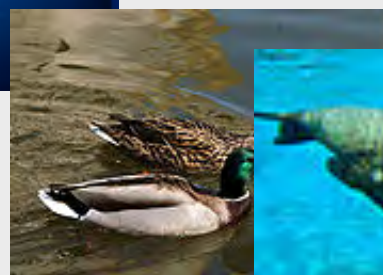
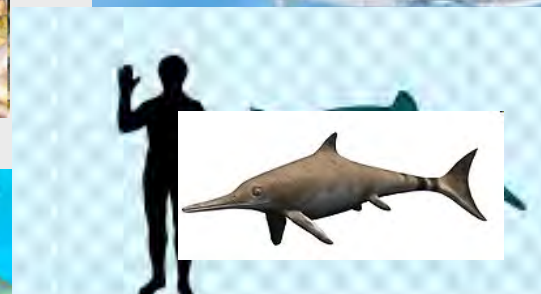
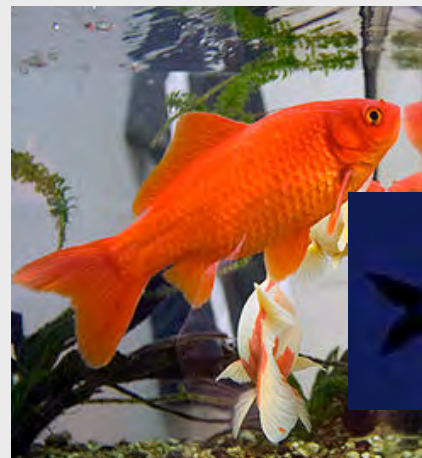
New kinds  
of machines



Tools for  
biologists



# Locomotion in water

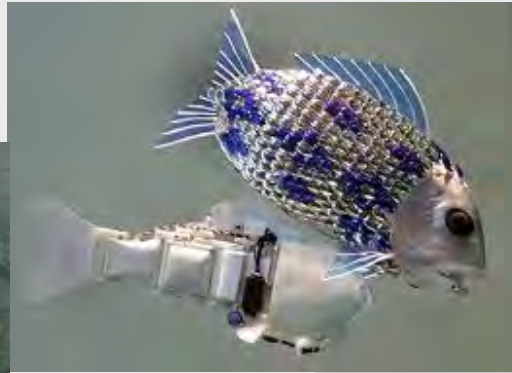




# Replicated by robots



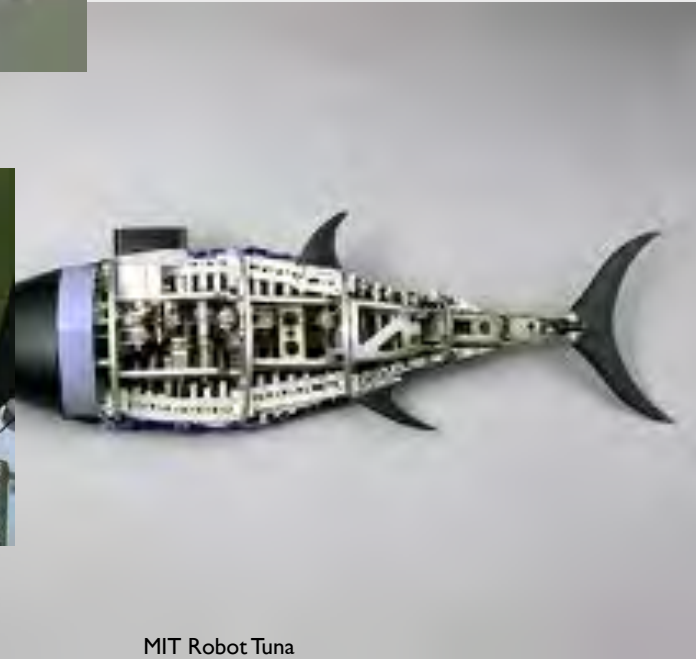
Ryomei Engineering, Koi carp robot



University of Essex



Ghost swimmer Boston Engineering

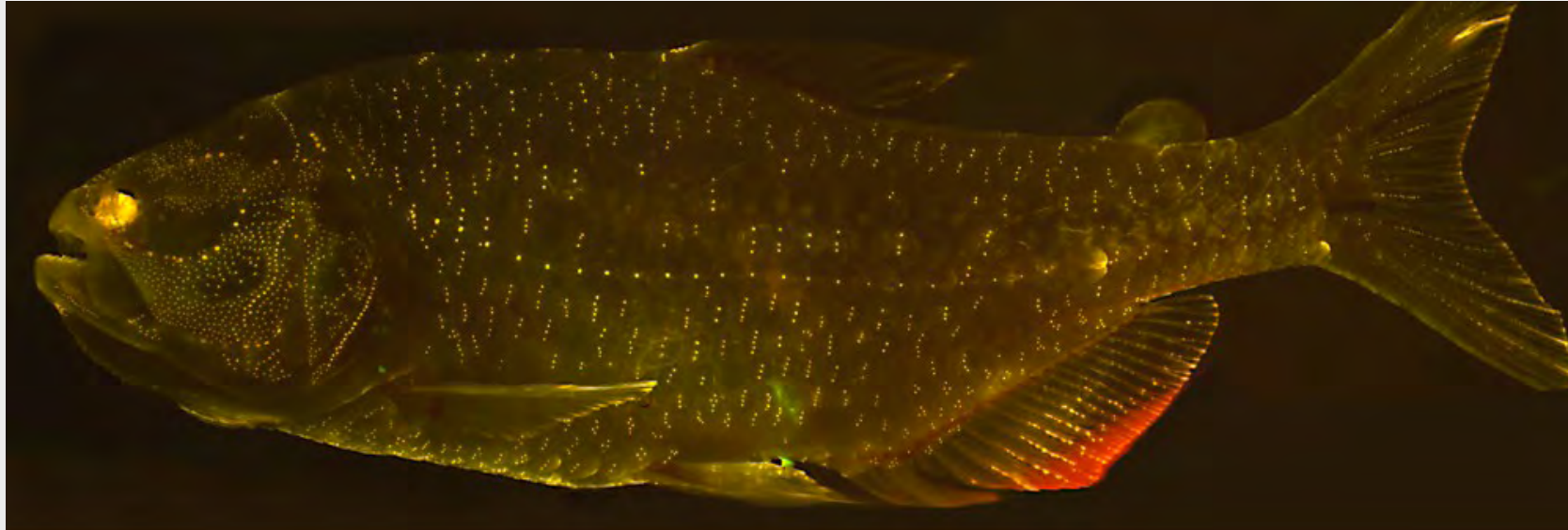


MIT Robot Tuna

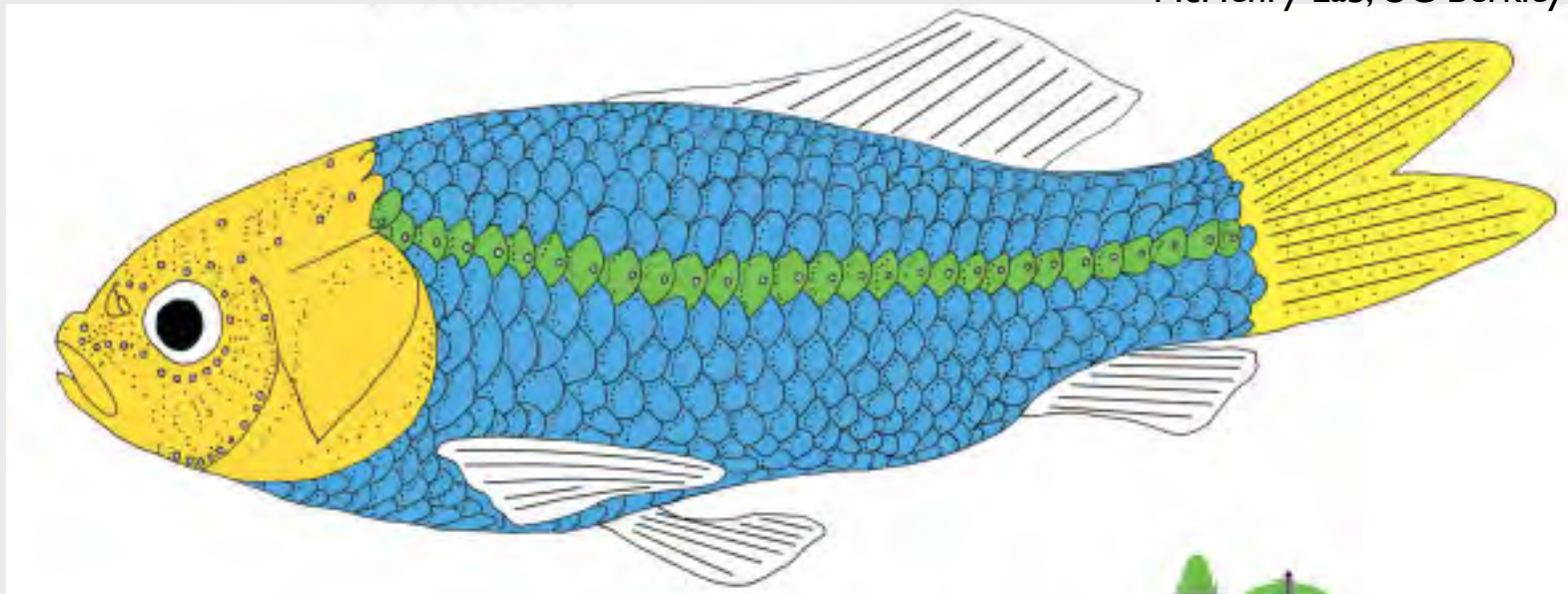


Festo Aqua ray

# What we have overlooked? Sensing!

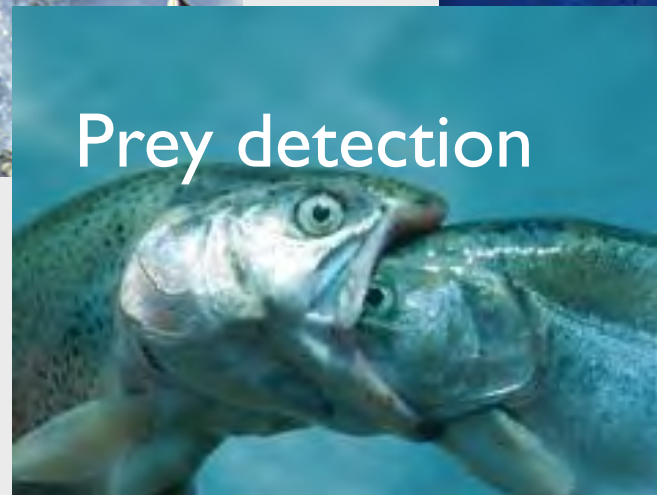
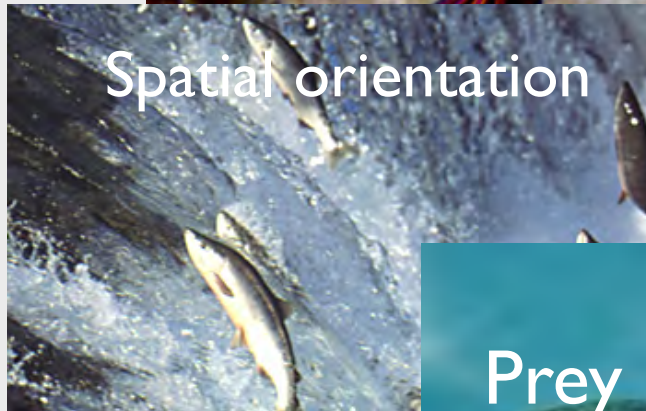


McHenry Lab, UC Berkley





# Medium is the message



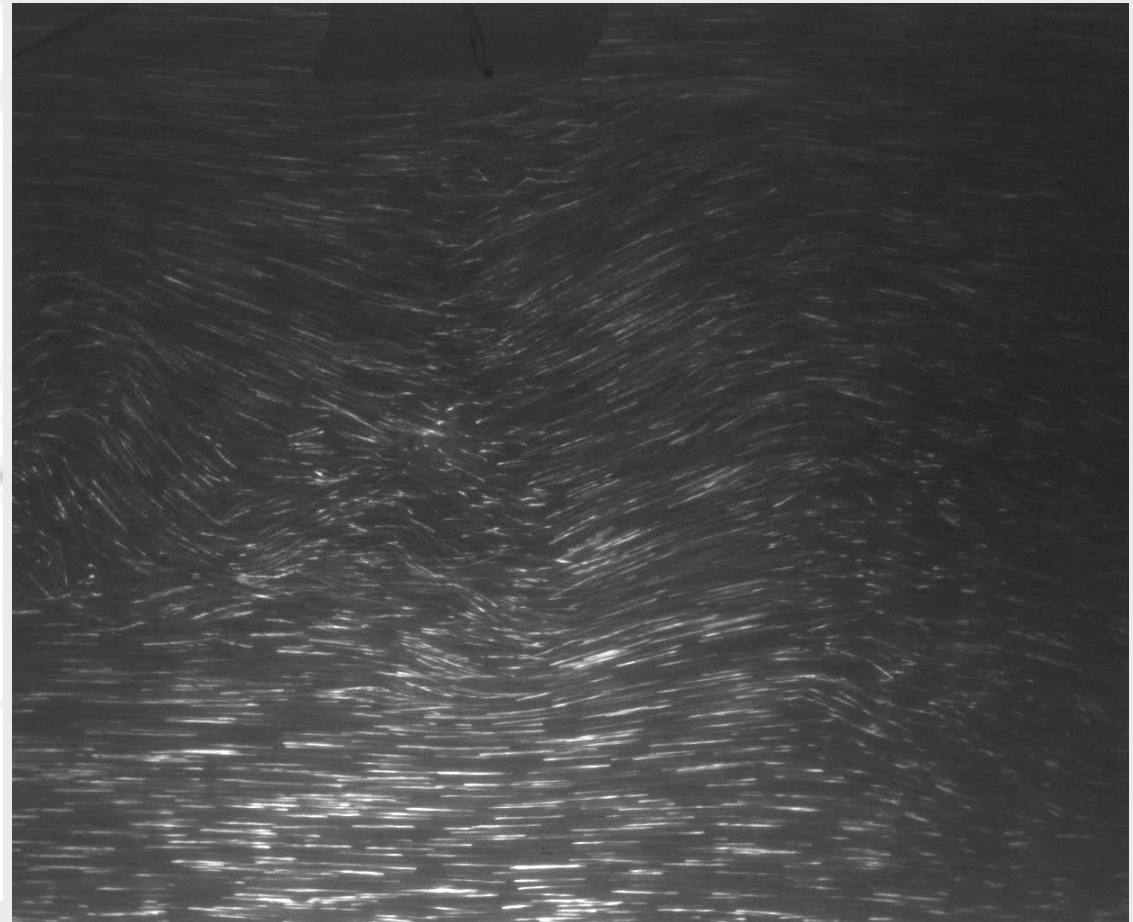
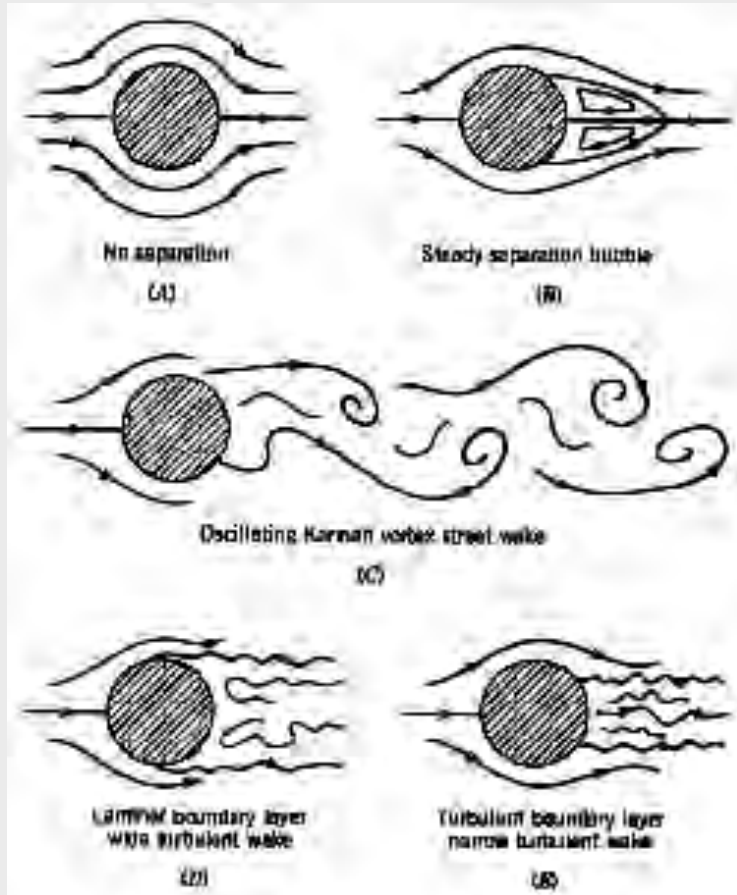


# How to make sense of the flow?



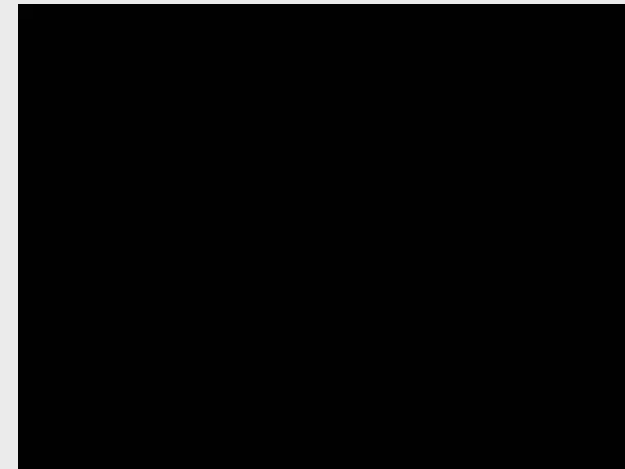


# Making sense of turbulence

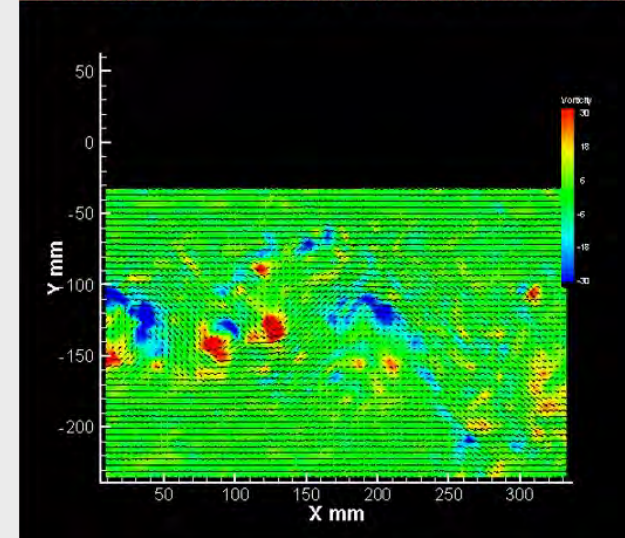




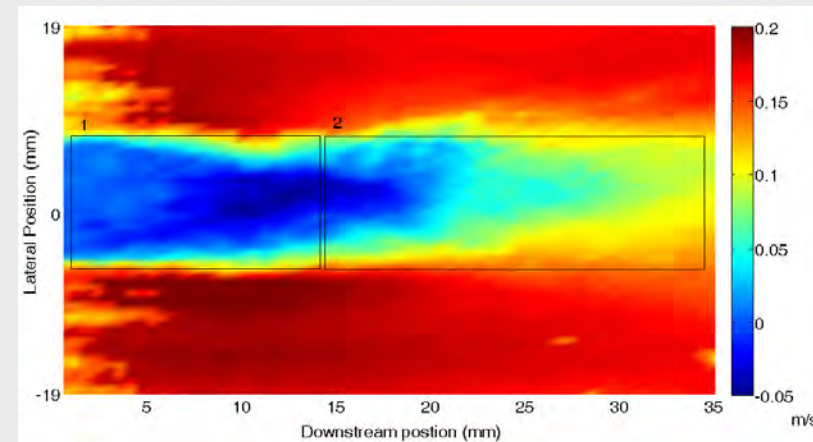
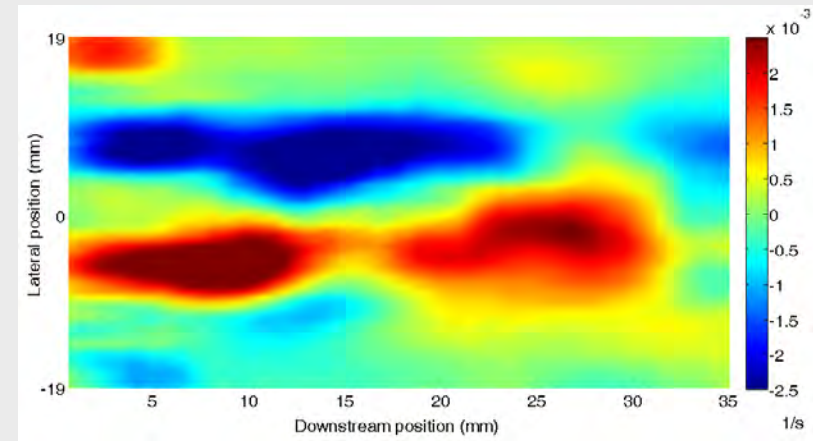
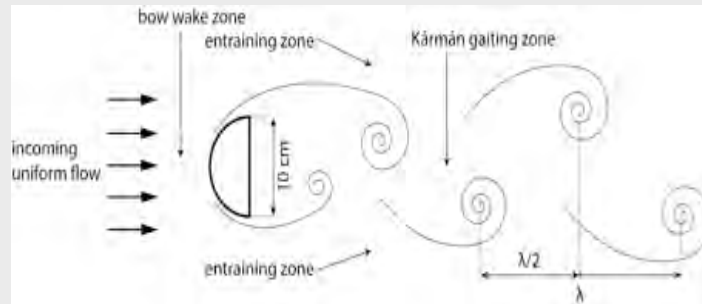
# Creating and controlling turbulence



Frame 001 | 27 Aug 2010 | C:\Experiments\but\_160710\_kvs\_critd\_ii50dciyl\_25cns\_nimronsetup\analysis50dciyl\_25

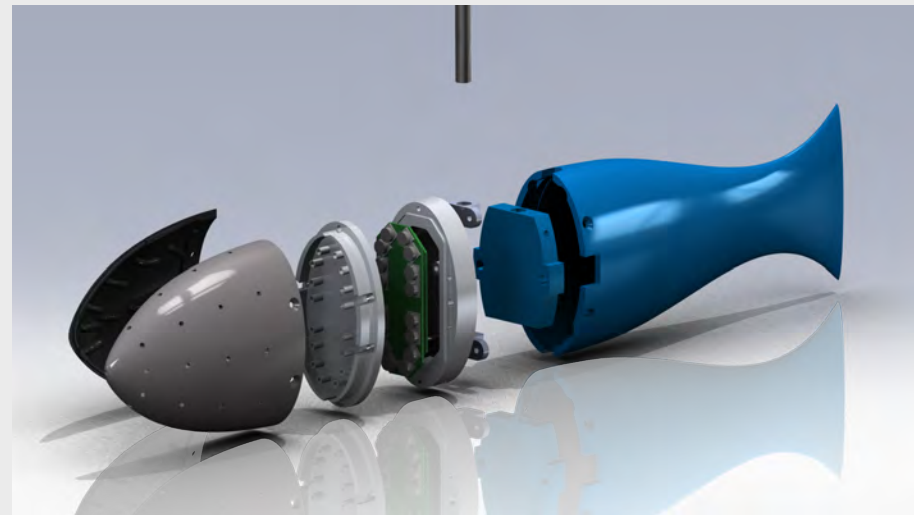
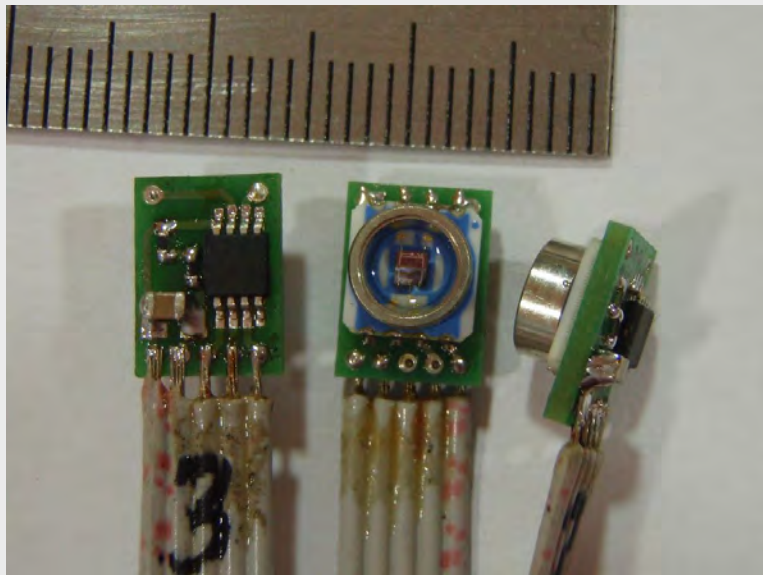


# Periodic turbulence – fairly simple but relevant

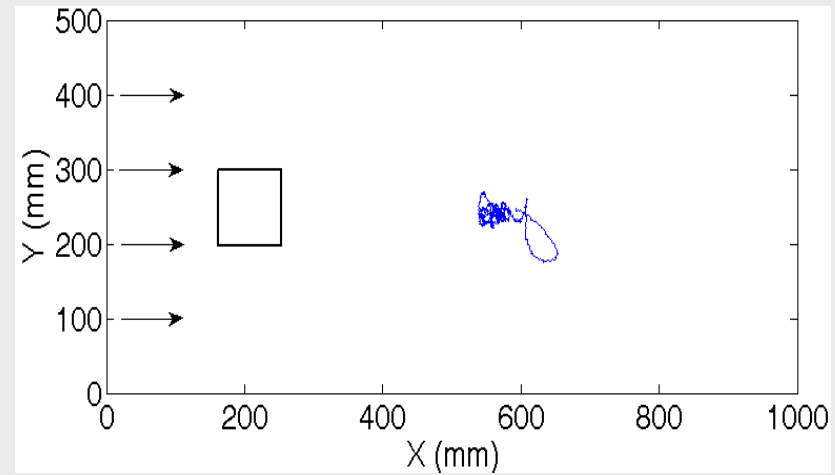
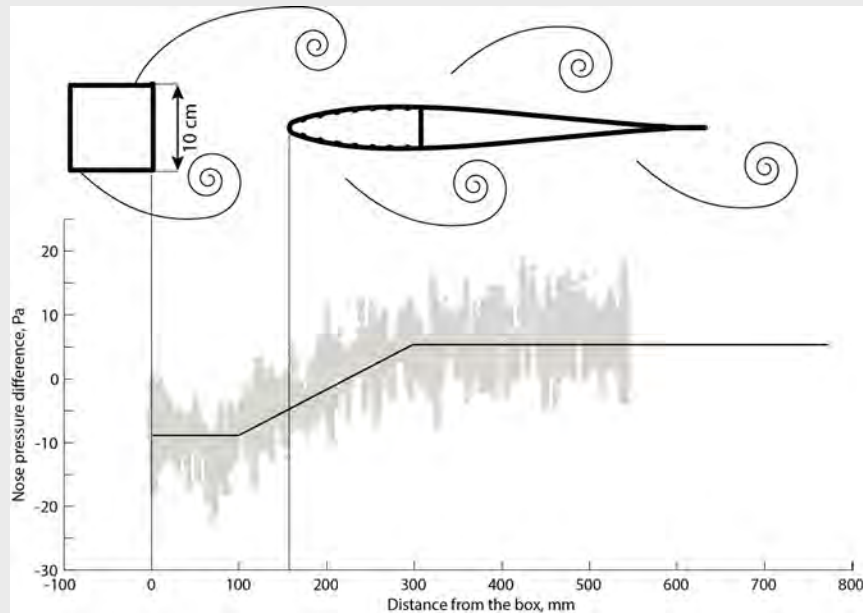




# New sense for robots



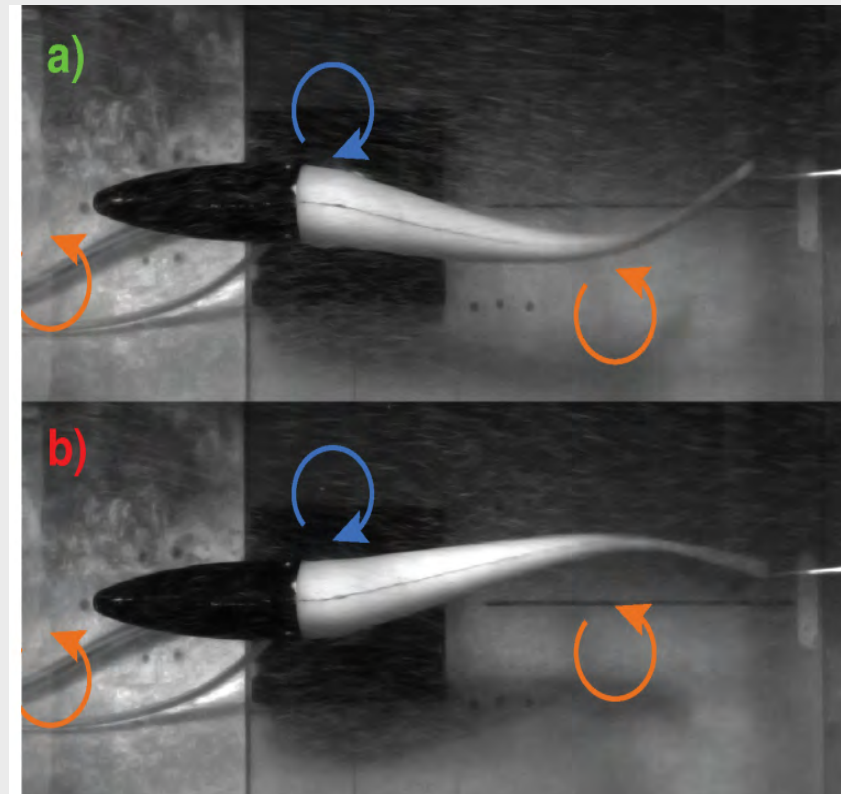
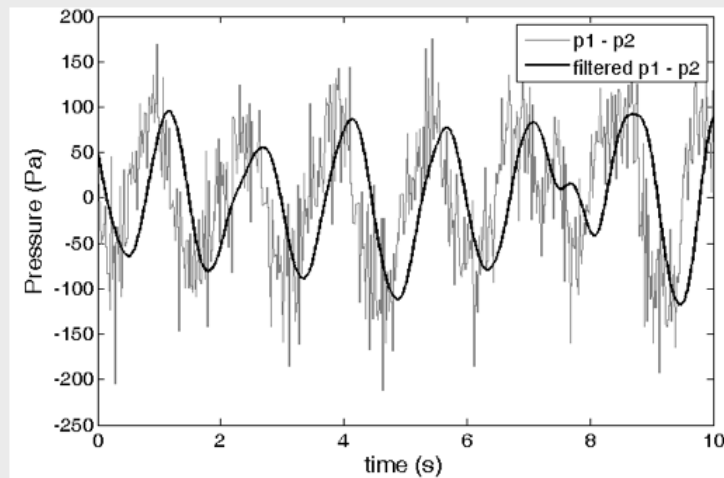
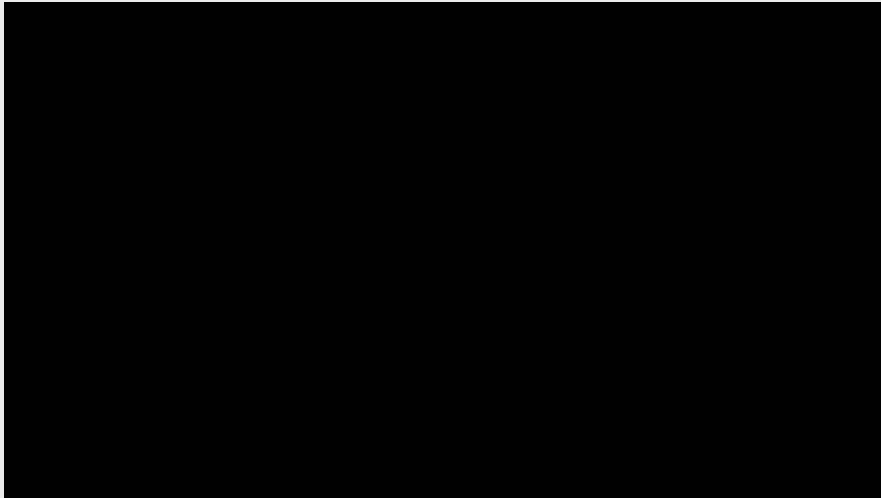
# Flow refuging



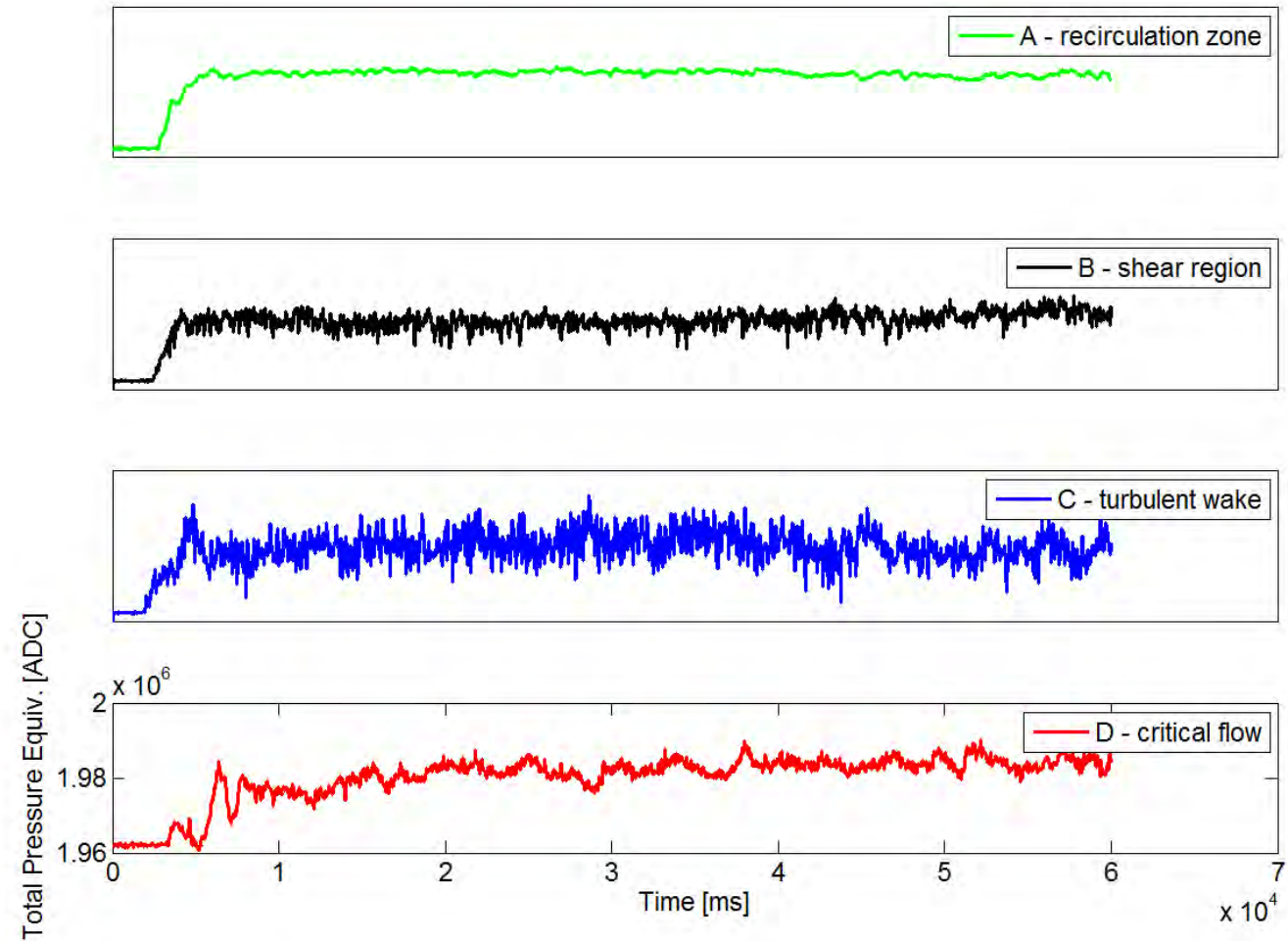
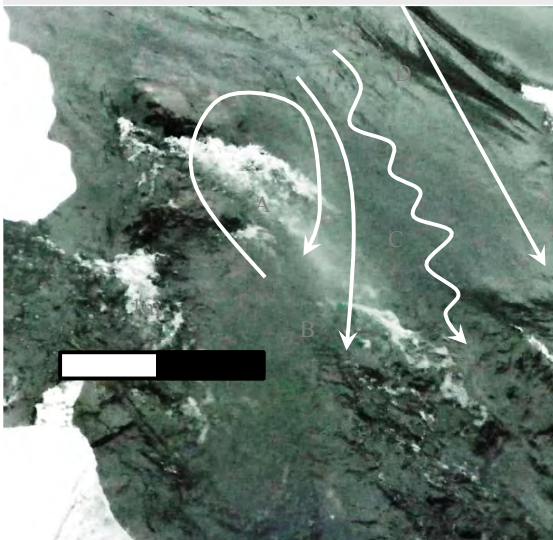
T. Salumäe, M. Kruusmaa, “Flow-relative control of an underwater robot”, in Proc. of the Royal Society”, to appear



# Sensing and interacting with vortices

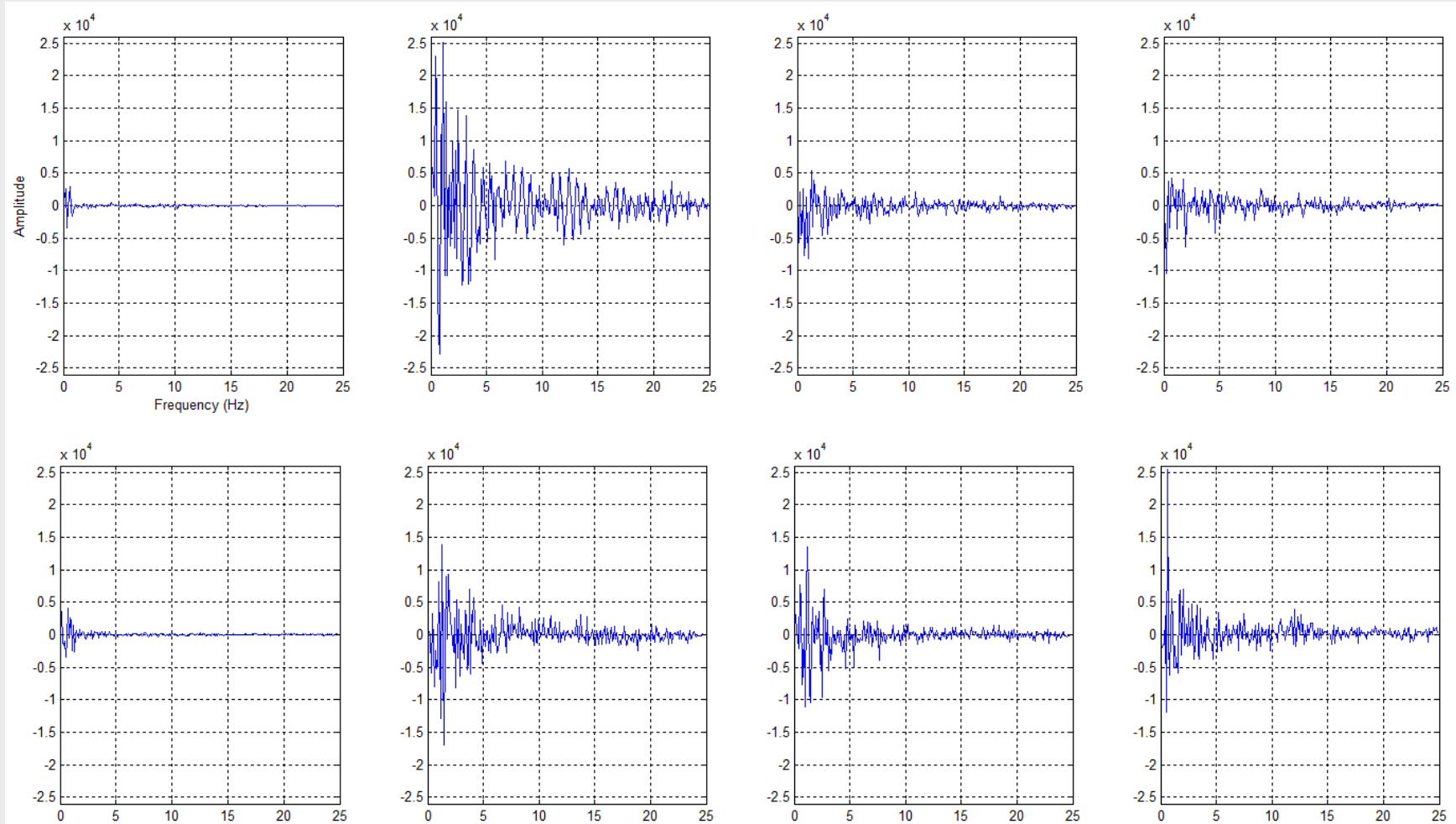


# Building flowscapes

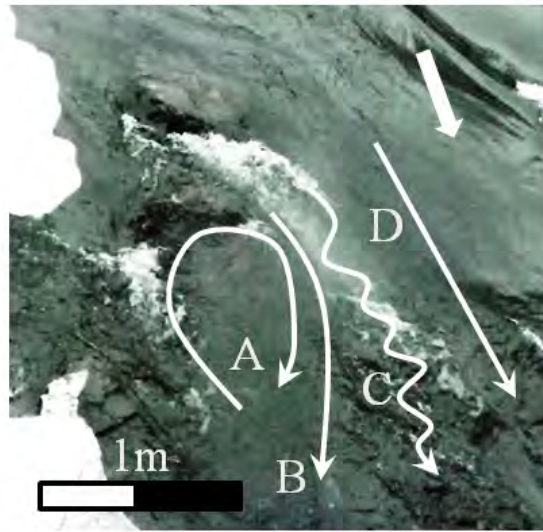




# Some number crunching – analysis in frequency domain - actually quite simple to be honest



# You can step in the same river twice



# How fish pass fishpasses? Or why they don't?





# Again, reducing complexity - semi-natural environment



# Natural environment





# U-CAT – turtle robot

